# Lecture #1: Newton's Method and Other Functional Hijinks

# Higher-Order Functions at Work: Iterative Update

A general strategy for solving an equation:

```
Gness a solution
while your guess isn't good enough:
   update your guess
```

- The three underlined segments are parameters to the process.
- The last two segments clearly require functions for their representation a predicate function (returning true/false values), and a function from values to values.
- In code,

```
def iter_solve(guess, done, update):
    """Return the result of repeatedly applying UPDATE,
    starting at GUESS, until DOME yields a true value
    when applied to the result."""
```

Last modified: Sun Feb 19 17:45:12 2017

CS198: Extra Lecture #1 1

CS198: Extra Lecture #1 2

#### Recursive Versions

Last modified: Sun Feb 19 17:45:12 2017

```
def iter_solve(guess, done, update):
    """Return the result of repeatedly applying UPDATE,
    starting at GUESS, until DONE yields a true value
    when applied to the result."""
    if done(guess):
        return guess
    else:
        return iter_solve(update(guess), done, update)
```

```
def iter.solve(guess, done, update):
    def solution(guess):
        if done(guess):
            return guess
        else:
            return solution(update(guess))
        return solution(guess))
```

Last modified: Sun Feb 19 17:45:12 2017

CS198: Extra Lecture #1 3

Last modified: Sun Feb 19 17:45:12 2017

CS198: Extra Lecture #1 4

#### Iterative Version

```
def iter.solve(guess, done, update):
    """Return the result of repeatedly applying UPDATE,
    starting at GUESS, until DONE yields a true value
    when applied to the result."""
    while not done(guess):
        guess = update(guess)
    return guess
```

### Adding a Safety Net

 In real life, we might want to make sure that the function doesn't just loop forever, getting no closer to a solution.

```
def iter_solve(guess, done, update, iteration_limit=32):
    """Return the result of repeatedly applying UPDATE,
    starting at GUESS, until DONE yields a true value
    when applied to the result. Causes error if more than
    ITERATION_LIMIT applications of UPDATE are necessary."""
```

## Adding a Safety Net: Code

In real life, we might want to make sure that the function doesn't just loop forever, getting no closer to a solution.

```
def iter_solve(guess, done, update, iteration_limit=32):
    """Return the result of repeatedly applying UPDATE,
    starting at OUESS, until DONE yields a true value
    when applied to the result. Causes error if more than
    ITERATION_LIMIT applications of UPDATE are necessary."""

def solution(guess, iteration_limit):
    if done(guess):
        return guess
    elif iteration_limit <= 0
        raise ValueError("failed to converge")
    else:
        return solution(update(guess), iteration_limit-1)
    return solution(guess, iteration_limit)</pre>
```

Last modified: Sun Feb 19 17:45:12 2017

CS198: Extra Lecture #1

Last modified: Sun Feb 19 17:45:12 2017

CS198: Extra Lecture #1

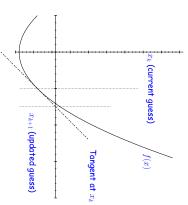
#### **Iterative Version**

Last modified: Sun Feb 19 17:45:12 2017

CS198: Extra Lecture #1

#### Newton's Method

 $\bullet$  Newton's method uses the basic iterative scheme with a particular update strategy to solve f(x)=0:



Last modified: Sun Feb 19 17:45:12 2017

CS198: Extra Lecture #1 8

# Using Iterative Solving For Newton's Method (I)

- Newton's method takes a function, its derivative, and an initial guess, and produces a result to some desired tolerance (that is, to some definition of "close enough").
- See http://en.wikipedia.org/wiki/File:NewtonIteration\_Ani.gif
- ullet Given a guess,  $x_k$ , compute the next guess,  $x_{k+1}$  by

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$$
 def newton\_solve(func, deriv, start, tolerance): """Return x such that  $|\text{FUNC}(\mathbf{x})| < \text{TOLERANCE, given initial estimate START and assuming DERIV is the derivatative of FUNC.""" def close_enough(x): ? def newton_update(x): ?$ 

Last modified: Sun Feb 19 17:45:12 2017

return iter\_solve(start, close\_enough, newton\_update)

CS198: Extra Lecture #1

# Using Iterative Solving for Newton's Method (II)

```
x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)} def newton_solve(func, deriv, start, tolerance): """Return x such that |\text{FUNC}(\mathbf{x})| < \text{TOLERANCE}, given initial estimate START and assuming DERIV is the derivatative of FUNC.""" def close_enough(x): return abs(func(x)) < tolerance def newton_update(x): return x - func(x) / deriv(x)
```

return iter\_solve(start, close\_enough, newton\_update)

Last modified: Sun Feb 19 17:45:12 2017

CS198: Extra Lecture #1 10

# Using newton solve for $\sqrt{\cdot}$ and $\lg \cdot$

## Dispensing With Derivatives

- What if we just want to work with a function, without knowing its derivative?
- Book uses an approximation:

```
def find_root(func, start=1, tolerance=le-5):
    def approx_deriv(f, delta = le-5):
        return lambda x: (func(x + delta) - func(x)) / delta
        return newton_solve(func, approx_deriv(func), start, tolerance)
```

- This is nice enough, but looks a little ad hoc (how did I pick delta?).
- Another alternative is the secant method.

Last modified: Sun Feb 19 17:45:12 2017 CS198: Extra Lecture #1 Last modified: Sun Feb 19 17:45:12 2017 CS198: Extra Lecture #1 12

#### The Secant Method

Newton's method was

$$x_{k+1} = x_k - \frac{f(x)}{f'(x)}$$

The secant method uses the last approximations values to get (in effect) a replacement for the derivative:

$$x_{k+1} = x_k - f(x_k) \frac{x_k - x_{k-1}}{f(x_k) - f(x_{k-1})}$$

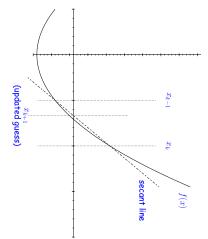
- See http://en.wikipedia.org/wiki/File:Secant\_method.svg
- But this is a problem for us: so far, we've only fed the update function the value of  $x_k$  each time. Here we also need  $x_{k-1}$ .
- ullet How do we generalize to allow arbitrary extra data (not just  $x_{k-1}$ )?

Last modified: Sun Feb 19 17:45:12 2017

CS198: Extra Lecture #1

13

## Secant Method Illustrated



Last modified: Sun Feb 19 17:45:12 2017

CS198: Extra Lecture #1 14

## Generalized iter\_solve

```
def
                                                                                                                                                      """Return the result of repeatedly applying UPDATE, starting at GUESS and STATE, until DONE yields a true value when applied to the result. Besides a guess, UPDATE also takes and returns a state value, which is also passed to
                                   while not done(guess, state):
    guess, state = update(guess, state)
return guess
                                                                                                                                                                                                                                                                                                                           iter_solve2(guess, done, update, state=None):
```

# Using Generalized iter\_solve2 for the Secant Method

The secant method:

$$x_{k+1} = x_k - f(x_k) \frac{x_k - x_{k-1}}{f(x_k) - f(x_{k-1})}$$
 def secant\_solve(func, start0, start1, tolerance): def close\_enough(x, state): return abs(func(x)) < tolerance def secant\_update(xk, xk1): return (xk - func(xk)) \* (xk - xk1) / (func(xk) - func(xk1)), xk) return iter\_solve2(start1, close\_enough, secant\_update, start0)

Last modified: Sun Feb 19 17:45:12 2017

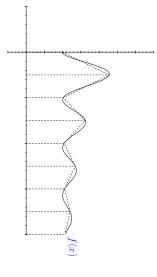
CS198: Extra Lecture #1 15

Last modified: Sun Feb 19 17:45:12 2017

CS198: Extra Lecture #1 16

## **Numerical Integration**

You may have encountered a method of approximately integrating functions using the trapezoidal rule:



So  $\int_0^4 f(x) dx$  is approximately the area under the dashed trapezoids.

# **Numerical Integration Method**

def integrate.trapezoidal(f, low, high, step):
"""An approximation to the definite intregral of F from
LOW to HIGH, computed by adding the areas of trapezoids of
height STEP."""

Last modified: Sun Feb 19 17:45:12 2017

CS198: Extra Lecture #1 17

Last modified: Sun Feb 19 17:45:12 2017

CS198: Extra Lecture #1 18

```
def integrate_trapezoidal(f, low, high, step):
    """An approximation to the definite intregral of F from
    LOW to HIGH, computed by adding the areas of trapezoids of
    height STEP."""
   Last modified: Sun Feb 19 17:45:12 2017
                                                                                                                                                                                                                                                                                                                                     \bullet The file e01\,.\,py has a few interesting variations on this.
                                                                                                                                                                                                                                                                                                                                                                                             area = 0
while low + step < high:
    area += (f(low) + f(low + step)) * step * 0.5
    low += step
    low += step
# Before returning, take care of the case where the final value
# of low is less than high.
return area + (f(low) + f(high)) * (high - low) * 0.5</pre>
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         Numerical Integration Method
CS198: Extra Lecture #1 19
```